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that $y_i[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k]$ (S2.1-1) The signals $x[n]$ and $h[n]$ are as shown in Figure S2.1. ,
- t W A 2 . 4 h W 3 0 t ^ - 1 0 i) 1 Figure S2.1 From this figure, we can easily see that the above convolution sum reduces to $y_i[n] = h[-1]x[n+1] + h[1]x[n-1] + \dots$

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systems The second operator H_{inv} is the inverse of the first operator H .

Hence, the input $x(t)$ is passed through the cascade connection of H and H_{inv} completely unchanged. Signals

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two situations equivalent, provided the H is time invariant.

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